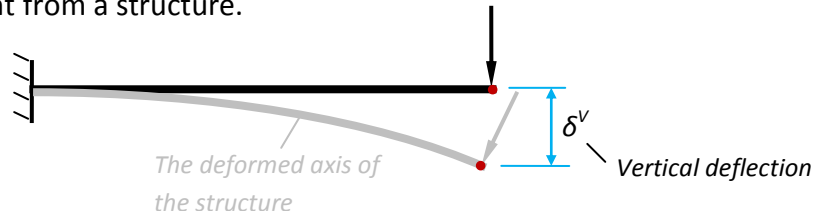


How to find vertical deflection in beam structures

Only 2D beam structures will be regarded below. Only vertical deflection will be discussed.

Vertical deflection is the vertical distance between a point from the undeformed axis of a structure and the same point which lies on the deformed axis. (see the picture below). The formula and the procedure which are described below allow obtaining the vertical deflection in a given point from a structure.



Finding vertical deflection is a task which contains the following steps:

- drawing the Free Body Diagram (FBD)
- determining the support reactions by using the equilibriums
- applying the method of the section to determine the internal forces by using the equilibriums (only M_z will be determined)
- determining the derivatives of the M_z
- applying the formulas for finding deflections

The following formula can be used for finding the vertical deflection in 2D loading in bending:

$$\delta_i^v = \int_L \frac{M_z}{E \cdot I_z} \cdot \frac{\partial M_z}{\partial F_i} \cdot dx$$

In the above formula:

δ_i^v - vertical deflection in the i -th point,

M_z - internal moment,

E - modulus of elasticity (Young's modulus),

I_z - moment of inertia of the cross-section,

$\frac{\partial M_z}{\partial F_i}$ - derivative of M_z with respect to the concentrated force in the i -th point.

The integration is along the length of the beam.

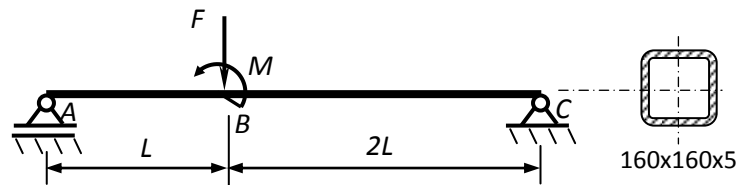
In order to find the **vertical deflection** in a given point there must be a **concentrated force** in this point.

IT IS IMPORTANT TO MAKE A LETTER SOLUTION (not to replace the parameters with their values) UNTIL SUBSTITUTING IN THE FORMULA!!!

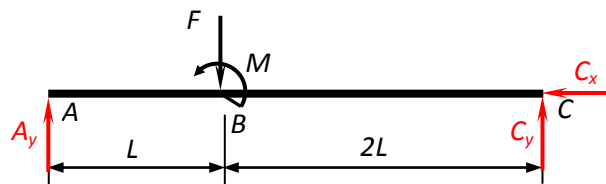
To demonstrate the above described procedure two examples will be regarded:

Example 1

Find the vertical deflection in point B ($\delta_B^y = ?$) if $F = 18 \text{ kN}$, $M = 6 \text{ kN.m}$, $L = 3 \text{ m}$. The cross-section is a standard square hollow section 160x160x5 according to EN 10210-2:2006. The material is ductile standard steel S235JR with modulus of elasticity $E = 2.10^{11} \text{ Pa}$.



1. FBD



2. Determining the support reactions by using the equilibriums

$$\sum F_x = 0 \Rightarrow \boxed{C_x = 0 \text{ kN}};$$

$$\sum F_y = 0 \Rightarrow A_y + C_y - F = 0 \Rightarrow A_y + C_y = F$$

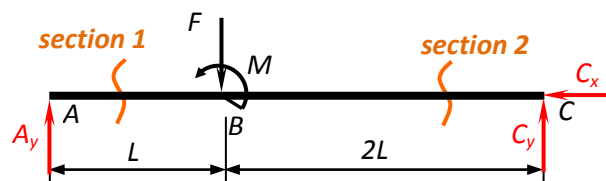
$$\sum M_{z_A} = 0 \Rightarrow M - F \cdot L + C_y \cdot 3L = 0 \Rightarrow C_y = \frac{F \cdot L}{3 \cdot L} - \frac{M}{3 \cdot L} \Rightarrow \boxed{C_y = \frac{F}{3} - \frac{M}{3 \cdot L}}$$

From the second equilibrium

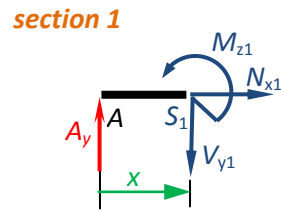
$$\Rightarrow A_y = F - C_y \Rightarrow A_y = F - \left(\frac{F}{3} - \frac{M}{3 \cdot L} \right) = \Rightarrow \boxed{A_y = \frac{2F}{3} + \frac{M}{3 \cdot L}}$$

3. Applying the method of the section to determine the internal forces by using the equilibriums

Two sections have to be made in the regarded example



The left part will be taken for **section 1**. The internal forces are drawn in the point of the section - S_1 .

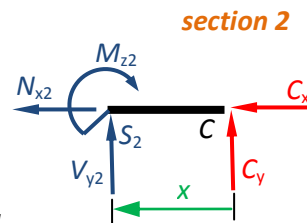


The boundaries of the coordinate x are: $0 \leq x \leq L$.

Since only M_z will be used in the formula this will be the only internal force to be determined.

$$\sum M_{z_{s1}} = 0 \Rightarrow M_{z1} - A_y \cdot x = 0 \Rightarrow M_{z1} = A_y \cdot x \Rightarrow M_{z1} = \left(\frac{2F}{3} + \frac{M}{3.L} \right) x \Rightarrow \boxed{M_{z1} = \frac{2F}{3}x + \frac{M}{3.L}x}$$

The right part will be taken for **section 2**. The internal forces are drawn in the point of the section - S_2 .



The boundaries of the coordinate x are: $0 \leq x \leq 2L$.

Again only M_z will be determined.

$$\sum M_{z_{s2}} = 0 \Rightarrow M_{z2} - C_y \cdot x = 0 \Rightarrow M_{z2} = C_y \cdot x \Rightarrow M_{z2} = \left(\frac{F}{3} - \frac{M}{3.L} \right) x \Rightarrow \boxed{M_{z2} = \frac{F}{3}x - \frac{M}{3.L}x}$$

4. Determining the derivatives of M_z

The formula for δ_B^V requires the derivative of M_{z1} and M_{z2} with respect to the force concentrated in point B to be determined.

The equation of M_{z1} is

$$M_{z1} = \frac{2F}{3}x + \frac{M}{3.L}x$$

The derivative of M_{z1} with respect to the concentrated in point B force is:

$$\boxed{\frac{\partial M_{z1}}{\partial F_B} = \frac{\partial M_{z1}}{\partial F} = \frac{2}{3}x}$$

Some comments on how to find derivatives of the internal moment:

In this type of problems the derivative of M_z can be found by taking into account with what is the force F multiplied in the expression for M_z , i.e. in the above expression for M_{z1} F is multiplied with $\frac{2}{3}x$

($M_{z1} = \frac{2F}{3}x + \frac{M}{3.L}x = \left(\frac{2}{3}x\right) \cdot F + \frac{M}{3.L}x$) and that is why $\frac{\partial M_{z1}}{\partial F} = \frac{2}{3}x$.

The equation of M_{z2} is

$$M_{z2} = \frac{F}{3}x - \frac{M}{3.L}x$$

Following the above explanations the derivative of M_{z2} can be found by accounting that F is multiplied with $\frac{1}{3}x$ in the expression for M_{z2} which means that

$$\boxed{\frac{\partial M_{z2}}{\partial F_B} = \frac{\partial M_{z2}}{\partial F} = \frac{1}{3}x}$$

5. Applying the formula for finding the deflection

Since the structure consists of 2 sections in the formula for δ_B^V 2 integrals will be used – one for the first section and one for the second one:

$$\delta_B^V = \int_0^L \frac{M_{z1}}{E.I_z} \cdot \frac{\partial M_{z1}}{\partial F_B} dx + \int_0^{2L} \frac{M_{z2}}{E.I_z} \cdot \frac{\partial M_{z2}}{\partial F_B} dx$$

It has to be minded that the boundaries of each integral coincide with the boundaries of each section.

Substituting the expressions for M_{z1} and M_{z2} and their derivatives with respect to F will give

$$\delta_B^V = \int_0^L \frac{\left(\frac{2F}{3}x + \frac{M}{3.L}x\right)}{E.I_z} \cdot \left(\frac{2}{3}x\right) dx + \int_0^{2L} \frac{\left(\frac{F}{3}x - \frac{M}{3.L}x\right)}{E.I_z} \cdot \left(\frac{1}{3}x\right) dx$$

Opening the parenthesis will lead to

$$\delta_B^V = \int_0^L \frac{\left(\frac{4F}{9}x^2 + \frac{2M}{9.L}x^2\right)}{E.I_z} dx + \int_0^{2L} \frac{\left(\frac{F}{9}x^2 - \frac{M}{9.L}x^2\right)}{E.I_z} dx$$

This expression can be divided into 4 integrals

$$\delta_B^V = \int_0^L \left(\frac{4F}{9} x^2 \right) \frac{dx}{E \cdot I_z} + \int_0^L \left(\frac{2M}{9 \cdot L} x^2 \right) \frac{dx}{E \cdot I_z} + \int_0^{2L} \left(\frac{F}{9} x^2 \right) \frac{dx}{E \cdot I_z} + \int_0^{2L} \left(\frac{-M}{9 \cdot L} x^2 \right) \frac{dx}{E \cdot I_z}$$

If all the constants are moved in front of the integrals it will follow

$$\delta_B^V = \frac{4F}{9 \cdot E \cdot I_z} \int_0^L x^2 dx + \frac{2M}{9 \cdot L \cdot E \cdot I_z} \int_0^L x^2 dx + \frac{F}{9 \cdot E \cdot I_z} \int_0^{2L} x^2 dx - \frac{M}{9 \cdot L \cdot E \cdot I_z} \int_0^{2L} x^2 dx$$

These integrals can be solved by using the following formula

$$\int_0^L x^n dx = \frac{x^{n+1}}{n+1} \Big|_0^L = \frac{L^{n+1}}{n+1} - \frac{0^{n+1}}{n+1} = \frac{L^{n+1}}{n+1}$$

that is

$$\delta_B^V = \frac{4F}{9 \cdot E \cdot I_z} \cdot \frac{L^3}{3} + \frac{2M}{9 \cdot L \cdot E \cdot I_z} \cdot \frac{L^3}{3} + \frac{F}{9 \cdot E \cdot I_z} \cdot \frac{(2L)^3}{3} - \frac{M}{9 \cdot L \cdot E \cdot I_z} \cdot \frac{(2L)^3}{3} = \frac{1}{9 \cdot E \cdot I_z} \left(4F \cdot \frac{L^3}{3} + \frac{2M}{L} \cdot \frac{L^3}{3} + F \cdot \frac{(2L)^3}{3} - \frac{M}{L} \cdot \frac{(2L)^3}{3} \right)$$

Now the parameters can be replaced with their values from the condition. It has to be minded that the units must be in [N], [m], [Pa].

The moment of inertia of the cross-section I_z can be taken from the tables. For the standard shape 160x160x5 according to EN 10210-2:2006 $I_z = 1225 \text{ cm}^4 = 1225 \cdot 10^{-8} \text{ m}^4$.

The loads are $F = 18 \text{ kN} = 18 \cdot 10^3 \text{ N}$, $M = 6 \text{ kN} \cdot \text{m} = 6 \cdot 10^3 \text{ N} \cdot \text{m}$

$$\delta_B^V = \frac{1}{9 \cdot 2 \cdot 10^{11} \cdot 1225 \cdot 10^{-8}} \left(4 \cdot 18 \cdot 10^3 \cdot \frac{3^3}{3} + \frac{2 \cdot 6 \cdot 10^3}{3} \cdot \frac{3^3}{3} + 18 \cdot 10^3 \cdot \frac{(2 \cdot 3)^3}{3} - \frac{6 \cdot 10^3}{3} \cdot \frac{(2 \cdot 3)^3}{3} \right)$$

$$\delta_B^V = \frac{1}{22050 \cdot 10^3} (648 \cdot 10^3 + 36 \cdot 10^3 + 1296 \cdot 10^3 - 144 \cdot 10^3) = \frac{1}{22050 \cdot 10^3} (1836 \cdot 10^3)$$

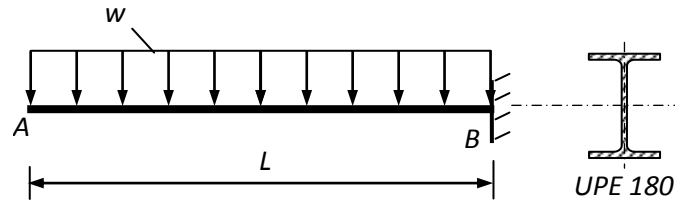
$$\delta_B^V = 0,0833 \text{ m}$$

The above example shows how to find the vertical deflection δ^V in a point in which there is a concentrated force.

The next example is related to cases in which the vertical deflection δ^V has to be determined in a point in which there is no concentrated force.

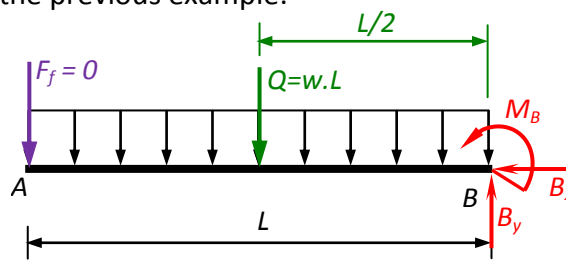
Example 2

Find the vertical deflection in point A ($\delta_A^V = ?$) if $w = 20 \text{ kN/m}$, $L = 2 \text{ m}$. The cross-section is a standard IPE shape – IPE 180. The material is ductile standard steel S235JR with modulus of elasticity $E = 2.10^{11} \text{ Pa}$.



1. FBD

In this example there is no concentrated force in point A which makes it impossible to find the derivative of M_z . In such cases a fictitious concentrated force F_f which value is equal to zero is added in the point where δ^V needs to be found. The solution continues according to the steps described in the previous example.



2. Determining the support reactions by using the equilibriums

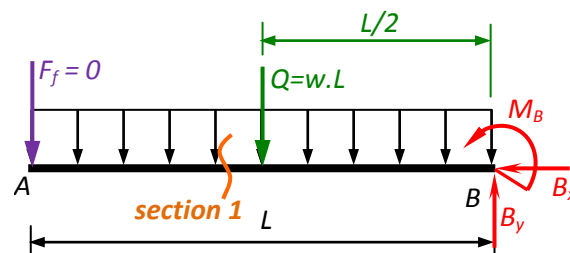
$$\sum F_x = 0 \Rightarrow \boxed{B_x = 0};$$

$$\sum F_y = 0 \Rightarrow B_y - Q - F_f = 0 \Rightarrow \boxed{B_y = w.L + F_f}.$$

$$\sum M_{z_C} = 0 \Rightarrow M_B + F_f.L + Q.\frac{L}{2} = 0 \Rightarrow \boxed{M_C = -F_f.L - w.L.\frac{L}{2}}$$

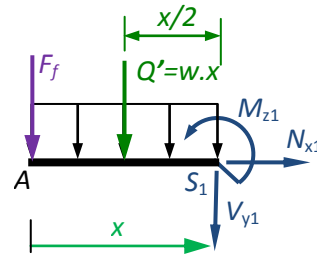
3. Applying the method of the section to determine the internal forces by using the equilibriums

One section is needed to determine the internal forces.



The left part will be taken for the section. The internal forces are drawn in the point of the section - S_1 .

section 1



The boundaries of the coordinate x are: $0 \leq x \leq L$.

Since only M_z will be used in the formula this will be the only internal force to be determined.

$$\sum M_{z_{s1}} = 0 \Rightarrow M_{z1} + F_f \cdot x + Q' \cdot \frac{x}{2} = 0 \Rightarrow M_{z1} = -F_f \cdot x - w \cdot x \cdot \frac{x}{2} \Rightarrow \boxed{M_{z1} = -F_f \cdot x - w \cdot \frac{x^2}{2}}$$

4. Determining the derivatives of M_z

Now the derivative of M_{z1} with respect to the force F_f which is concentrated in point A (the point where δ_A^V is searched) can be determined. (To find this it has to be accounted with what F_f is multiplied in the expression of M_{z1})

$$\boxed{\frac{\partial M_{z1}}{\partial F_A} = \frac{\partial M_{z1}}{\partial F_f} = -x}$$

5. Applying the formula for finding the deflection

The formula for δ_A^V consists of one integral which boundaries are the same as the boundaries of the section:

$$\delta_A^V = \int_0^L \frac{M_{z1}}{E \cdot I_z} \cdot \frac{\partial M_{z1}}{\partial F_A} dx$$

Substituting the expression for M_{z1} and its derivative with respect to F_f will give

$$\delta_A^V = \int_0^L \frac{\left(-F_f \cdot x - w \cdot \frac{x^2}{2} \right)}{E \cdot I_z} \cdot (-x) dx$$

This integral can be simplified when accounting that F_f is zero:

$$\delta_A^V = \int_0^L \frac{\left(-w \cdot \frac{x^2}{2} \right)}{E \cdot I_z} \cdot (-x) dx$$

Opening the parenthesis and moving the constants out of the integral will lead to:

$$\delta_A^V = \frac{w}{2.E.I_z} \int_0^L x^3 dx = \frac{w}{2.E.I_z} \frac{L^4}{4}$$

Now the parameters can be replaced with their values from the condition. It has to be minded that the units must be [N], [m], [Pa].

The moment of inertia of the cross-section I_z can be taken from the tables. For the standard IPE shape IPE 180 $I_z = 1317 \text{ cm}^4 = 1317 \cdot 10^{-8} \text{ m}^4$.

The load is $w = 20 \text{ kN/m} = 20 \cdot 10^3 \text{ N/m}$.

$$\delta_A^V = \frac{20 \cdot 10^3}{2 \cdot 2 \cdot 10^{11} \cdot 1317 \cdot 10^{-8}} \frac{2^4}{4} \quad \Rightarrow \quad \boxed{\delta_A^V = 0,0152 \text{ m}}$$